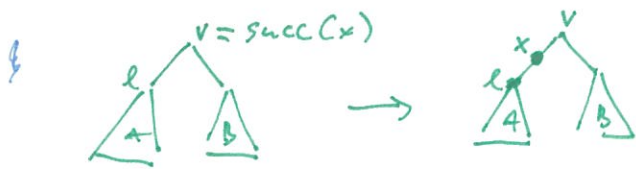


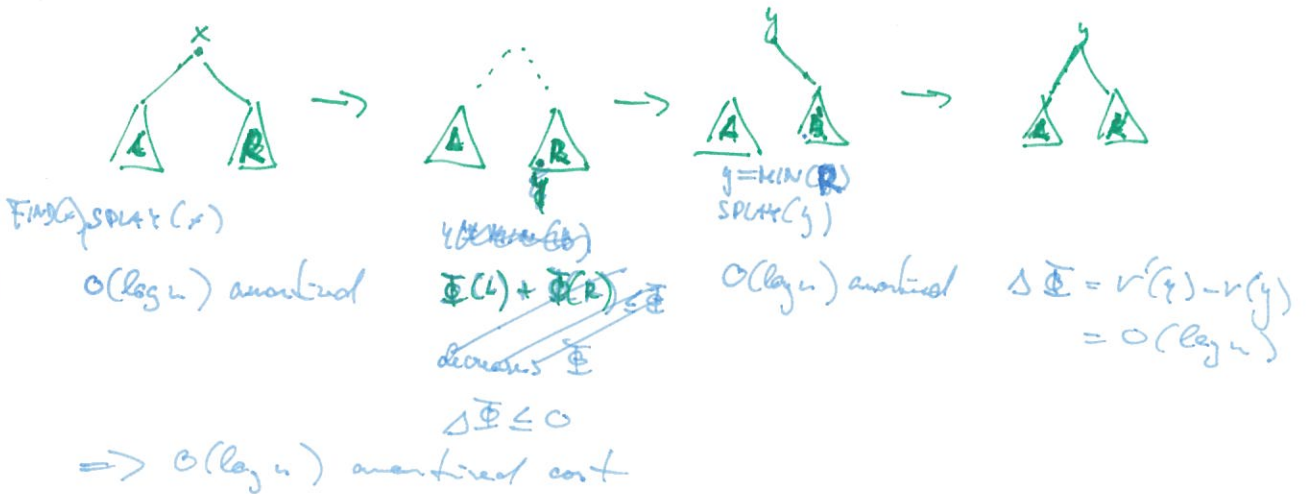
Alternative INSERT + DELETE



only $r'(v), r'(x)$ are modified
 $\Rightarrow \Delta \Phi = O(\log n)$

- **INSERT(x)**: finds $v = \text{succ}(x)$, $\text{SPLIT}(v)$, add x
 $\Rightarrow O(\log n)$ amortized cost

- **DELETE(x)**: **FIND(x)**, **SPLIT(x)**, remove x , $y = \text{MIN}(B)$, **SPLIT(y)**

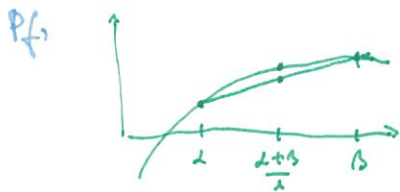


Analysis of SPLIT

Theorem: The amortized cost of **SPLIT(x)** is at most $3(r'(x) - r(x)) + 1$.

Claim: $2C246 / 2C216$ amortized cost $\leq 3(r'(x) - r(x)) + 1$ (Helioscopy)

Lemma: For any $x, b > 0$, $\log \frac{x+b}{2} \geq \frac{\log x + \log b}{2}$.



concavity of \log
 (second derivative is $-1/x^2$, negative)
 [Jensen's inequality special case]

$\Rightarrow \log x + \log b \leq 2 \log \frac{x+b}{2}$ (1) \rightarrow to compute the real cost

2C246: $A \leq 2 + r'(w) + r'(x) + r'(y) - r(w) - r(x) - r(y) \leq 2r'(x) - 2$

$r'(w) + r'(y) = \log \left(\frac{s'(w)}{s'(x)} \right) + \log \left(\frac{s'(y)}{s'(x)} \right) \leq 2 \log \left(\frac{s'(w) + s'(y)}{s'(x)} \right) - 2$

$r(w) + r(y) \geq 2r(x)$ since $T(w), T(y) \leq T(x)$

$\Rightarrow A \leq 2 + 2r'(x) - 2 + r'(x) - r(x) - 2r(x) = 3(r'(x) - r(x))$ ✓

2.6.216:

$$A = 2 + r'(x) + r'(y) + r'(z) - r(x) - r(y) - r(z)$$

all vertices \leftarrow $r(x) + r'(z) = \log s(x) + \log s'(z) \leq 2 \log (s(x) + s'(z)) - 2 \leq 2r'(x) - 2$

bst \leftarrow $\leq 2r'(x) - 2$

$$\Rightarrow A \leq 3r'(x) + r'(y) - 2r(x) - r(y) - r(z) \leq 3(r'(x) - r(x)) \checkmark$$

$\leq r'(y) \geq r(x) = r'(x)$

2.6.3

$$A = 1 + r'(x) + r'(y) - r(x) - r(y) \leq 1 + 2r'(x) - 2r(x) \leq 3(r'(x) - r(x)) + 1$$

$\leq r'(x) \geq r(x)$ as $r'(x) - r(x) \geq 0 \quad T(x) \leq T'(x)$

Weighted analysis

\leftarrow to compare with static optimal trees.

generalized potential: $w(x) > 0$ weight of x (ex: $w(x) = p(x)$)
 $S(x) = \sum_{v \in T(x)} w(v)$ size (\dots prob. distrib.)
 can be arbitrarily \rightarrow $r(x) = \log_2 S(x)$ rank
 small / large $\Phi = \sum_x r(x)$ potential

lemma: The (weighted) amortized cost of SPLAY(x) is at least $3(r'(x) - r(x)) + 1 = O(\log(W/w(x)) + 1)$ where $W = \sum_x w(x)$.

Pf: Since all weights positive, $T(u) \subseteq T(v) \Rightarrow S(u) \leq S(v), r(u) \leq r(v)$.
 \Rightarrow the previous proof works generally. (monotonicity)
 $r'(x) = \log W, r(x) = \log S(x) \leq \log w(x)$ implies \square

Ex. $w(x) = 1/n$ (uniform distribution) $\Rightarrow W = 1$
 $1/n \leq S(x) \leq 1, -\log n \leq r(x) \leq 0, -n \log n \leq \Phi \leq 0.$

\Rightarrow SPLAY(x) amortized $O(\log 1/(1/n) + 1) = O(\log n)$

\Rightarrow sequence of splays real cost $O((n + n) \log n)$.

\uparrow
 $n \log n$ for -4Φ .

Optimal static BST (interview) No (INSERT/DELETE) / updates

$T \sim \text{BST}$, $C_T(x) = \# \text{ nodes visited when accessing } x \text{ in } T$ ($C_T(x) = 1$ if x is root)
for x_1, \dots, x_n

$P \dots$ prob. distribution, $p(x) \dots$ prob. of accessing x

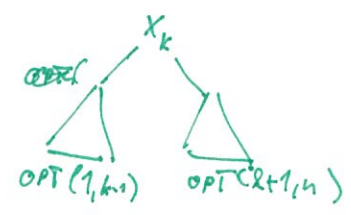
average access cost in $T = \mathbb{E}_x(C_T(x)) \dots$ minimized by OPT
optimal static BST

Construction of OPT = OPT(1, n)

$\text{OPT}(i, j) \dots$ optimal for $\{x_i, \dots, x_j\}$
(empty if $i > j$)

$C_{ij} = \mathbb{E}_x(C_{\text{OPT}(i,j)}(x))$ optimal cost

$r_{ij} = k$ s.t. x_k is the root of $\text{OPT}(i, j)$



dynamic algorithm: $\Rightarrow O(n^3)$ time

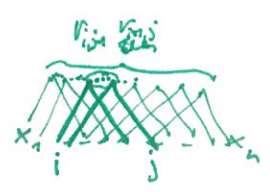
$C_{ii} := p(x_i), r_{ii} = i$

for $l = 2 \dots n-1$ interval length $+1$

for $i = 1 \dots n-l, j = i+l$ int. start, end

$C_{ij} = \min_{i \leq k \leq j} C_{i, k-1} + C_{k+1, j} + \sum_{i \leq m \leq j} p(x_m)$

$r_{ij} = \text{arg min}_{i \leq k \leq j} k$



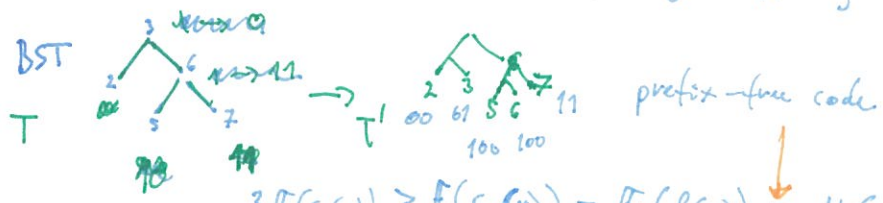
Kent's inequality: $r_{i, j-1} \leq r_{ij} \leq r_{i+1, j} \Rightarrow O(n^2)$ time
(exercise)

Splay trees vs optimal static BST (information theoretic bound)

$w(x) = p(x) \dots$ given prob. distribution p , $w=1$

\Rightarrow amortized cost of access of $x = O(\log(1/p(x)) + 1)$

\Rightarrow expected amortized cost $\mathbb{E}[O(\log(1/p(x)) + 1)] = O(1 + \sum_x p(x) \log \frac{1}{p(x)})$



$3 \mathbb{E}(C_T(x)) \geq \mathbb{E}(C_{\text{OPT}}(x)) = \mathbb{E}(l(x)) \geq H(p)$

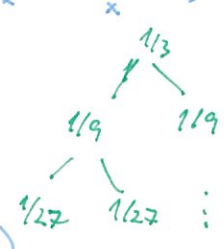
$H(p)$ entropy
 $= O(\mathbb{E}(C_{\text{OPT}}(x)))$

Theorem (static optimality): For any static BST T on a set X and any access sequence x_1, \dots, x_m where $f(x) > 0$ is the frequency of $x = x_i$, the total cost of accesses m in a Splay tree is $O(\sum_x f(x) c_T(x))$.

Pf: We set $w(x) := 3^{-c_T(x)}$ $\Rightarrow W = \sum_x w(x) \leftarrow \sum_{i=1}^{\infty} \frac{2^{i-1}}{3^i} = \frac{1}{2} \sum_{i=1}^{\infty} (\frac{2}{3})^i = 1$

$\Rightarrow r(x) = \log s(x) \leq \log W < 0$
 $\Phi = \sum_x r(x) < 0$

$\Rightarrow r(x) = \log s(x) \geq \log w(x) = \Theta(-c_T(x))$
 $\Leftrightarrow \Phi = \sum_x r(x) \geq -\Theta(\sum_x c_T(x))$



total cost in T
 ↑
 i-f-b tree
 $(\sum_{i=1}^{\infty} q_i = \frac{1}{1-q})$ for $0 < q < 1$

By Lemma, amortized cost $SPLAY(x)$ is

$$O(\log(W/w(x)) + 1) = O(\log \frac{1}{w(x)} + 1) = O(c_T(x) + 1) = O(c_T(x))$$

So, total real cost of access $:-$ $\ast SPLAY(x)$ is

$$O(\sum_x f(x) c_T(x)) - \frac{\Delta \Phi}{\Phi_m - \Phi_0} = O(\sum_x f(x) c_T(x)) - \frac{\Phi_m - \Phi_0}{\Phi_m - \Phi_0} = O(\sum_x f(x) c_T(x))$$

$O(\sum_x f(x)) < 0$ as $f(x) > 0$

Open Question: Are splay trees also dynamically optimal?

(within a constant factor of any dynamic tree that knows the sequence ahead of time)

Working set bound

access sequence x_1, \dots, x_m \Rightarrow distinct elements accessed since last occurrence of x_i

$z_i :=$ working set of x_i (distinct elements, ~~if it has~~ 1st occurrence) = all previous items if 1st occurrence

Theorem (working set bound): A splay tree on n items processes any access sequence x_1, \dots, x_m in time $O(n \log n + m + \sum_{i=1}^m \log(1+z_i))$.

idea: ~~$\frac{1}{z_i}$~~ (no proof) \Rightarrow good for cache

[Note: Splay trees good for nonuniform distributions, other trees (AVL) min on constants on uniform distributions.]