

Introduction to Artificial Intelligence

English practicals 3: Constraint satisfaction

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Approaches for solving algorithmic problems

Specialized algorithms

- Dijkstra's shortest path algorithm
- Hungarian algorithm for the assignment problem
- Prim's algorithm for minimum spanning tree

Is there an algorithm for every problem?

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- Infinitely many but countable algorithms
- Uncountable decision problems
- An algorithm does not exist for most of the problems
- There is no algorithm deciding whether a given program stops (The Halting problem)

Approaches for solving algorithmic problems

General approaches for solving problems

- What class of problems to solve?
- How to encode problems of this class?
- Find a general algorithm for solving this class of problems

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Examples of problem classes

- (Integer) linear programming (ILP)
- Constraint satisfaction programming (CSP)
- SAT (logical formulae in CNF)

A small reminder

- Problem solving is realized via **search**
- **Tree** search vs **graph** search
- **Uninformed** search - DFS, BFS, Uniform cost search vs **Informed** search - Best first search, A*
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- A **feasible solution** to a CSP is a complete consistent assignment of values to variables
- The arc (V_i, V_j) is arc consistent iff for each value x from the domain D_i there exists a value y in the domain D_j such that the assignment $V_i = x$ and $V_j = y$ satisfies all the binary constraints on V_i, V_j .

Selected quiz questions

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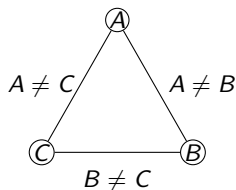
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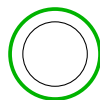
$$D_B = \{1,2\}$$

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Example: DFS

- Variables: $\{A, B, C\}$
- Domains: $D_A = D_B = D_C = \{1, 2, 3\}$
- Constraints:
 - $A > B$
 - $B \neq C$
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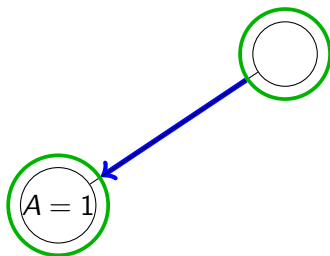
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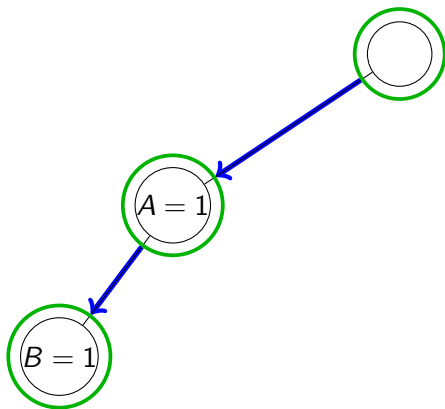
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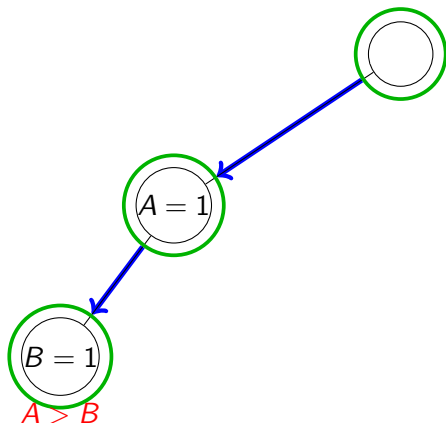
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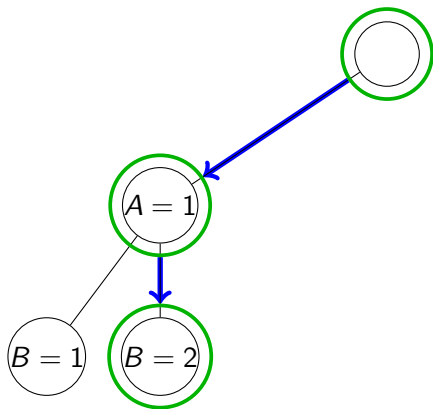
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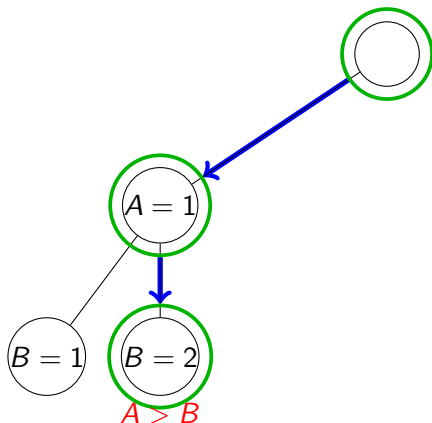
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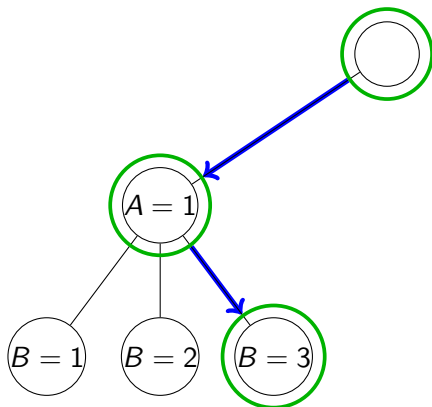
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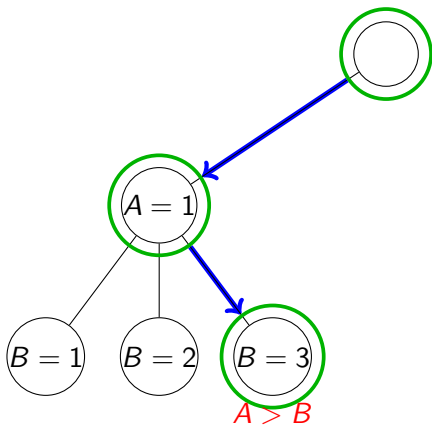
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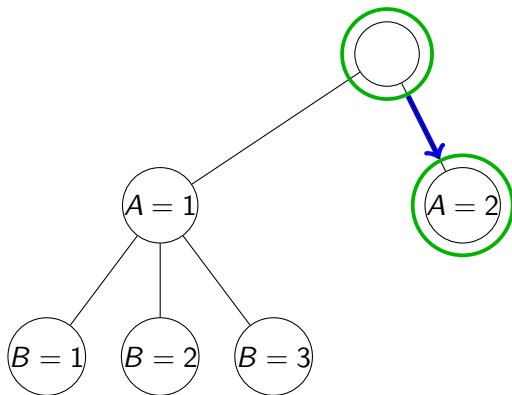
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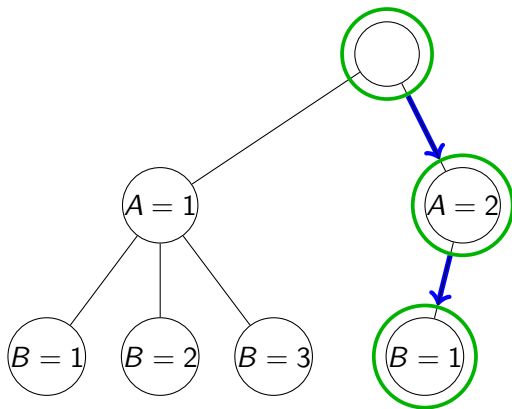
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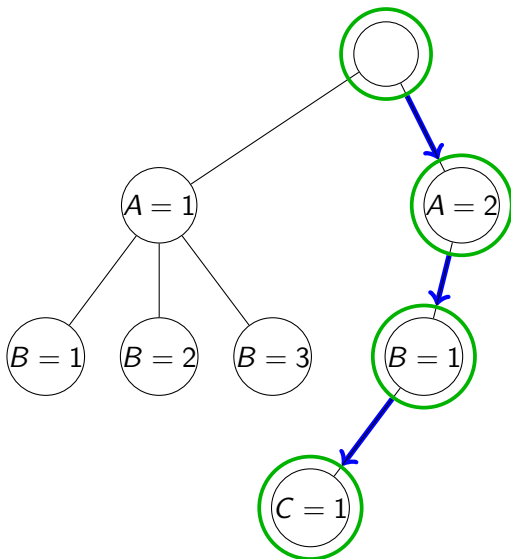
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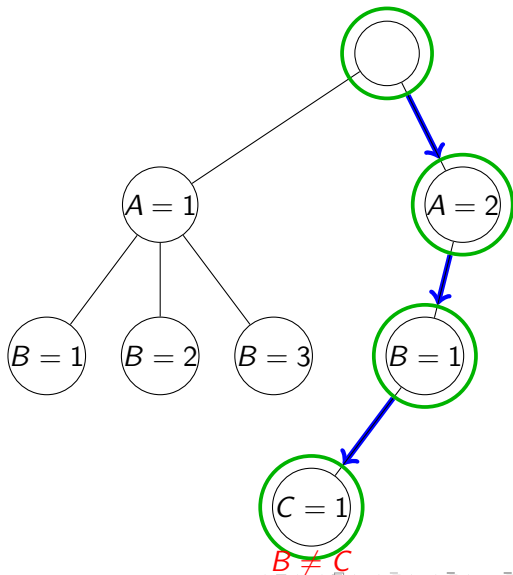
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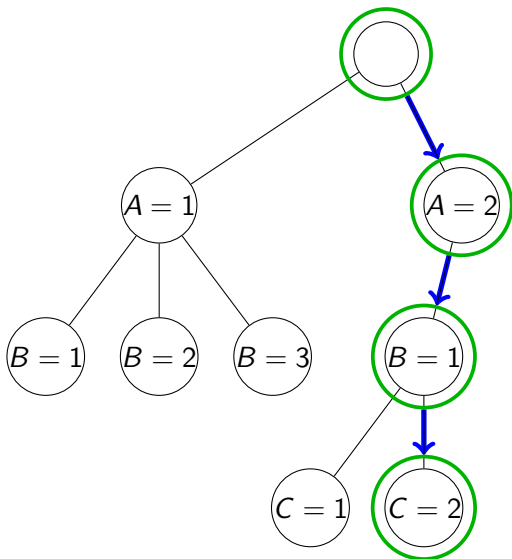
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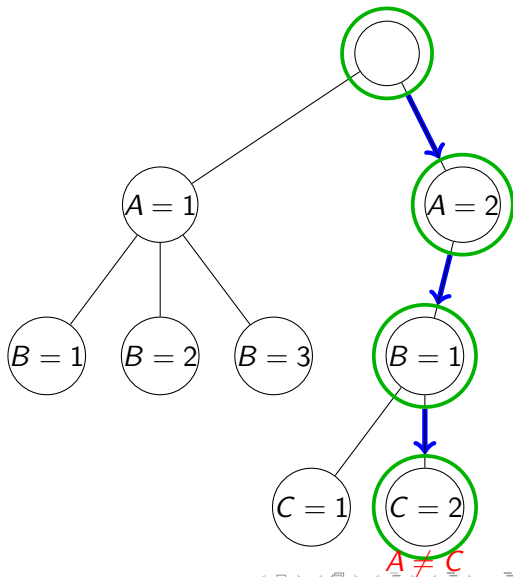
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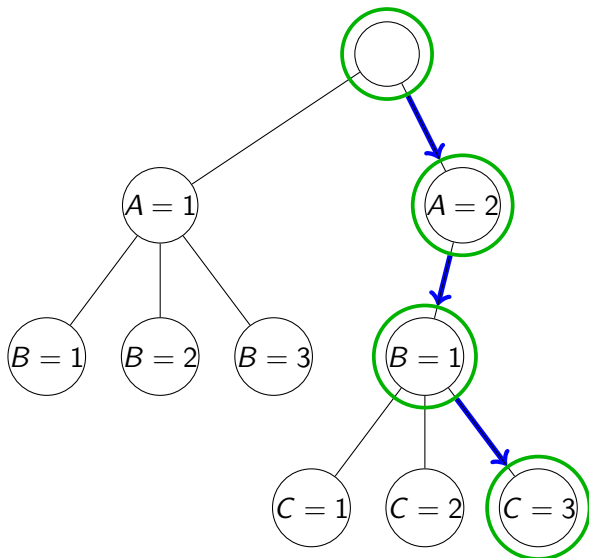
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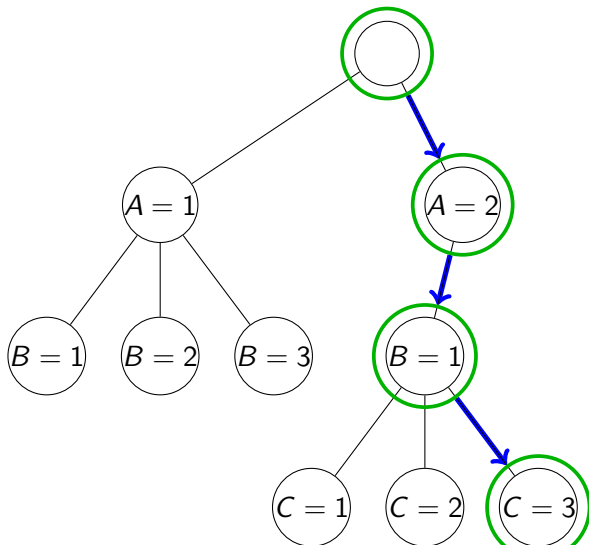
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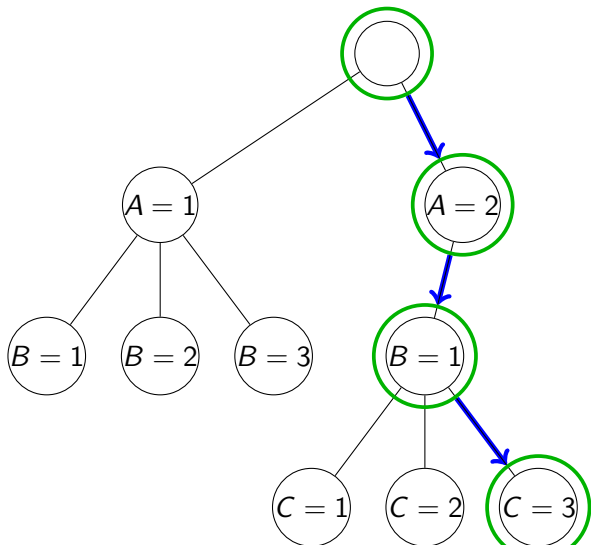
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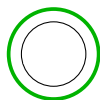
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- Feasible solution:
 $A = 2$
 $B = 1$
 $C = 3$



Example: forward checking

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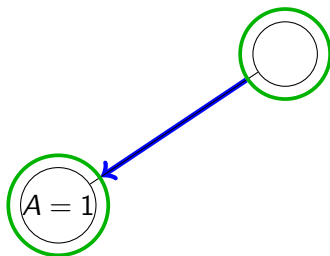
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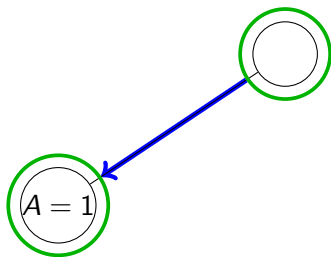
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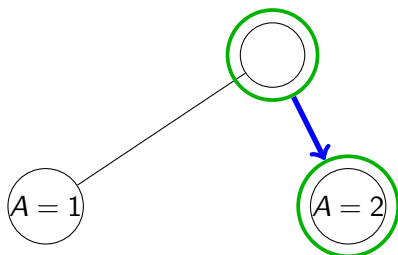
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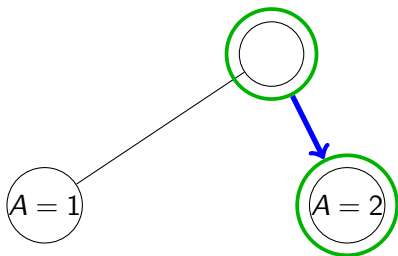
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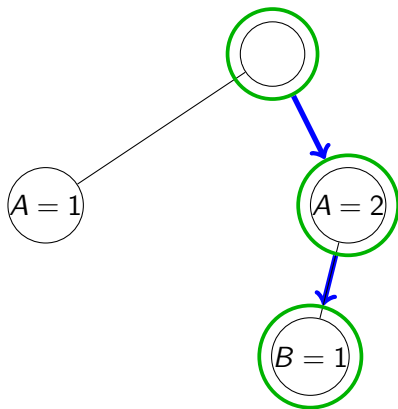
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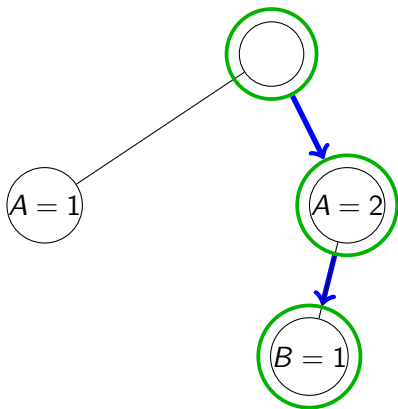
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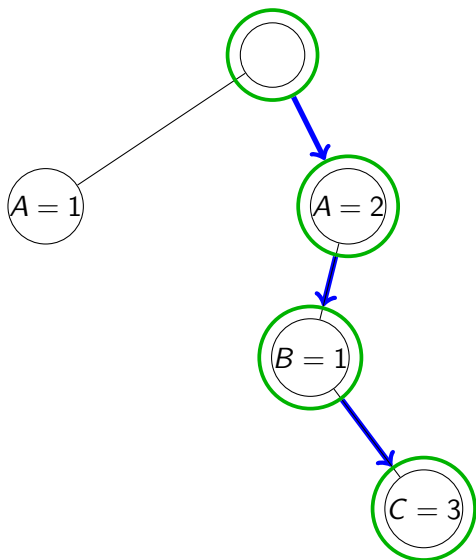
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- Turn each binary constraint into two arcs
($A < B$ becomes $A < B$ and $B > A$)
- Add all arcs to queue Q
- Repeat until Q is empty:
 - remove an arc (X_i, X_j) from Q and check if for every value of X_i there is a value in X_j
 - remove any inconsistent values from X_j
 - if the domain of X_j changed, add all arcs (X_k, X_j) to Q

Example: AC-3

- Variables:

$\{A, B, C\}$

Q

- Domains:

$D_A = \{1, 2, 3\}$

$D_B = \{1, 2, 3\}$

$D_C = \{1, 2, 3\}$

- Constraints:

$A > B$

$B = C$

Arcs:

Example: AC-3

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$D_B = \{1, 2, \}$

$D_C = \{1, 2, 3\}$

- Constraints:

$A > B$

$B = C$

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Arcs:

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Example: AC-3

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$\{A, B, C\}$

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Empty Q - the problem is arc consistent.

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Will the algorithm always terminate?

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defined by

$$\forall x_{ij} \in X : x_{ij} \in C_j, x_{ij} \in R_i, x_{ij} \in B_{(i-1)/3+1, (j-1)/3+1}$$

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- Each variable evaluation satisfying all constraints corresponds to a solution to a given sudoku instance and vice versa

Modelling example: Perfect matching

Perfect matching

A perfect matching in a graph $G = (V, E)$ is a subset $M \subseteq E$ in which every vertex in V is incident to exactly one edge in M .

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Formulation for bipartite graphs

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- Bipartite graph with node sets A and B with $|A| = |B|$

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- Constraints: $\forall a, a' \in A$ such that $a \neq a'$: $x_a \neq x_{a'}$